

Chapter 9 – Slice Selection and Multidimensional Imaging

Jaladhar Neelavalli, Ph.D.
Assistant Professor,
WSU SOM - Dept. of Radiology

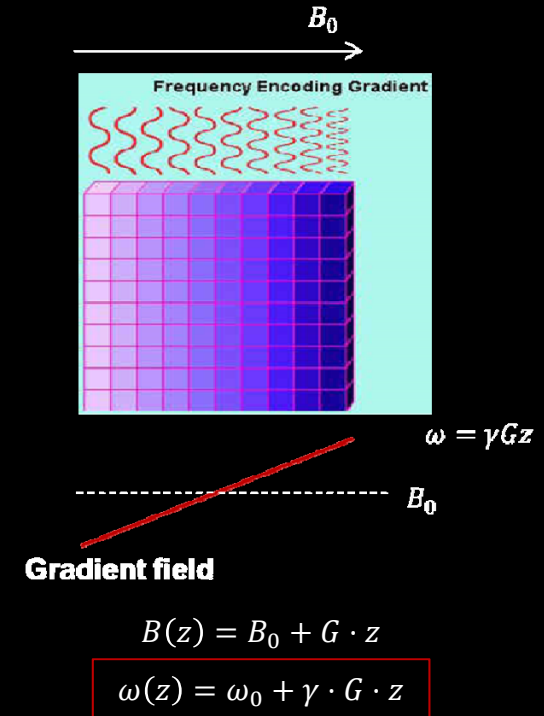
Quick Recap:

$$S(t) = \Lambda \cdot \omega_0 \cdot \beta_{\perp} \int d^3r \cdot M_{\perp}(\vec{r}, 0) \cdot e^{i(\Omega - \omega(\vec{r}, t))t}$$

$$S(t) = \int d^3r \cdot \rho(\vec{r}) \cdot e^{i(\Omega - \omega(\vec{r}, t))t}$$

$$\rho(\vec{r}) = \Lambda \cdot \omega_0 \cdot \beta_{\perp} \cdot M_0(\vec{r}) = \Lambda \cdot \omega_0 \cdot \beta_{\perp} \cdot \rho_0(\vec{r}) \frac{\gamma^2 \cdot \hbar^2 \cdot B_0}{4 \cdot k \cdot T}$$

... the effective spin density



$$\phi(\vec{r}, t) = \int_0^t (\Omega - \omega(\vec{r}, t')) \cdot dt'$$

$$\Omega = \omega_0 \quad \omega(\vec{r}, t) = \omega_0 + \Delta\omega(\vec{r}, t) \quad \omega(z) = \omega_0 + \gamma \cdot G \cdot z$$

$$\phi(\vec{r}, t) = \int_0^t -\Delta\omega(\vec{r}, t') \cdot dt'$$

$$\phi(z, t) = \int_0^t -\gamma \cdot G \cdot z \cdot dt'$$

$$\Rightarrow \phi(z, t) = -\gamma \cdot G \cdot z \cdot t$$

$$S(t) = \int dz \cdot \rho(z) \cdot e^{-i \cdot \gamma \cdot G \cdot z \cdot t}$$

Quick Recap:

$$S(t) = \int dz \cdot \rho(z) \cdot e^{-i \cdot \gamma \cdot G \cdot z \cdot t}$$

$$\phi(z, t) = 2\pi \cdot k \cdot t \quad k = \frac{\gamma}{2\pi} \cdot G \cdot t \quad k = \bar{\gamma} \cdot G \cdot t \quad \bar{\gamma} \equiv \frac{\gamma}{2\pi}$$

$$S(t) = S(k) = \int dz \cdot \rho(z) \cdot e^{-i \cdot 2\pi \cdot k \cdot z}$$

... the 1D imaging equation

$$k(t) = \int_0^t \bar{\gamma} \cdot G(t') \cdot dt' \quad \phi(z, t) = -2\pi \cdot k(t) \cdot z$$

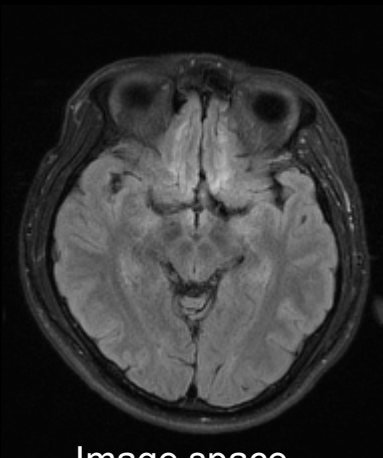
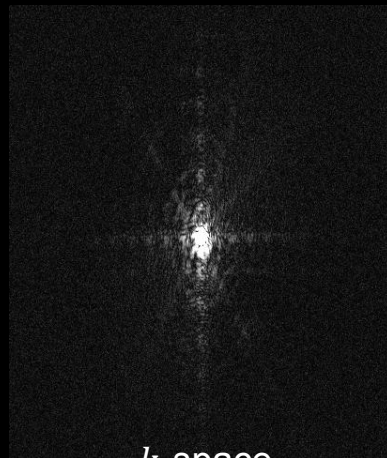


Image space



k -space

Units of k variable...

$$\frac{\text{rad}}{\text{sec} \cdot \text{Tesla}} \cdot \frac{1}{\text{rad}} \cdot \frac{\text{Tesla}}{\text{meter}} \cdot \text{sec} \equiv \frac{1}{\text{meter}}$$

Quick Recap:

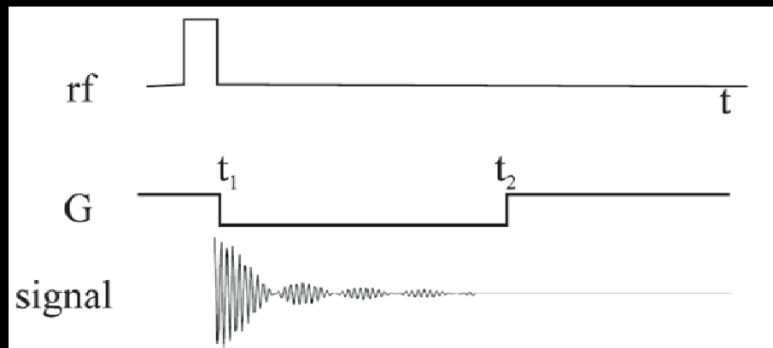
Fourier Transform Pair

$$S(t) = S(k) = \int_{-\infty}^{+\infty} dz \cdot \rho(z) \cdot e^{-i \cdot 2\pi \cdot k \cdot z}$$

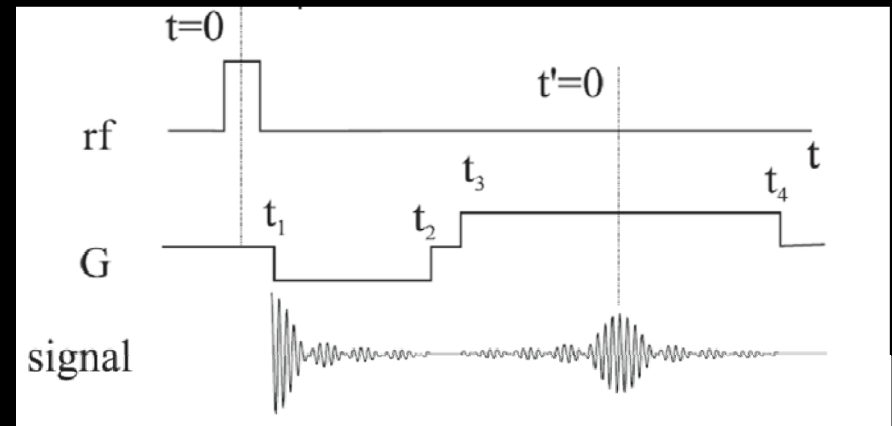
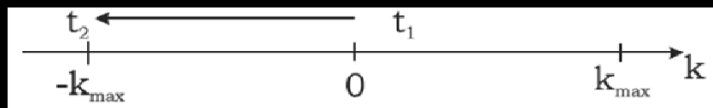
Inverse Fourier Transform...

$$\rho(z) = \int_{-\infty}^{+\infty} dk \cdot S(k) \cdot e^{+i \cdot 2\pi \cdot k \cdot z}$$

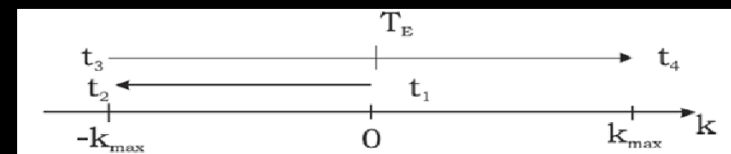
1D imaging experiment with Gradient Echo



$$k = \bar{\gamma} \cdot -G \cdot t \quad t_1 < t < t_2$$

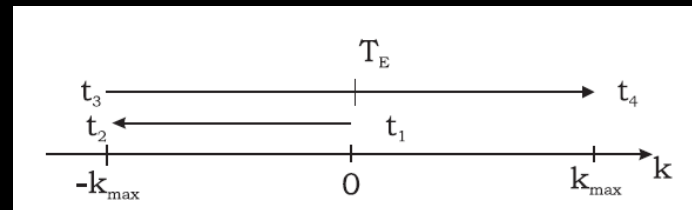
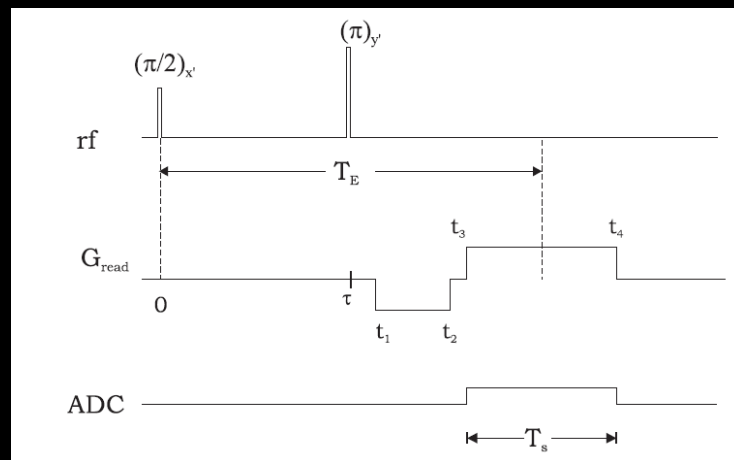
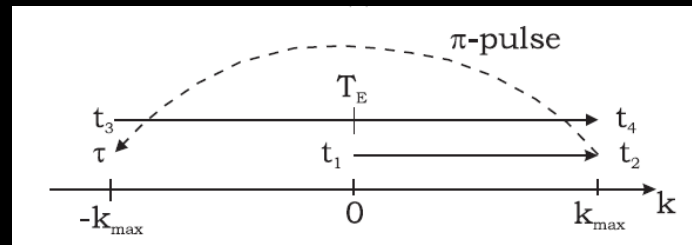
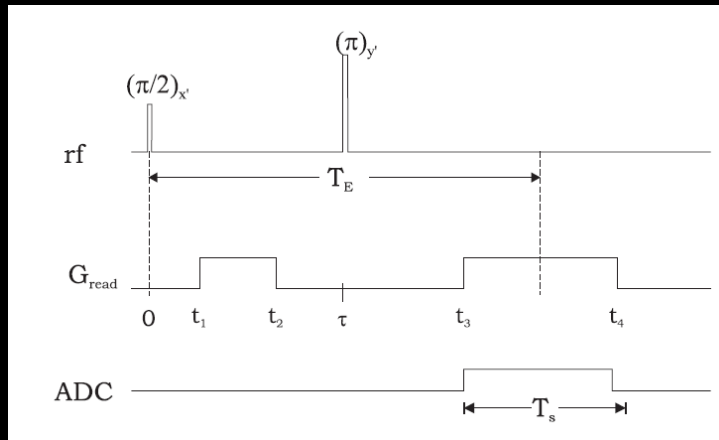


$$k = \bar{\gamma} \cdot G \cdot t \quad t_3 < t < t_4$$

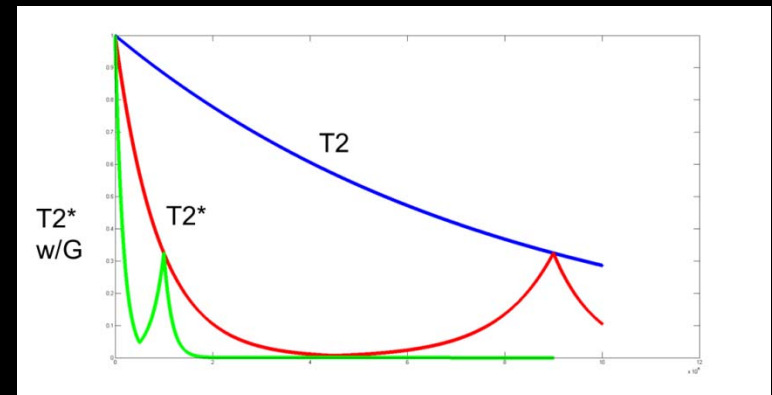


Quick Recap:

1D imaging experiment using a Gradient Echo coinciding with the Spin Echo



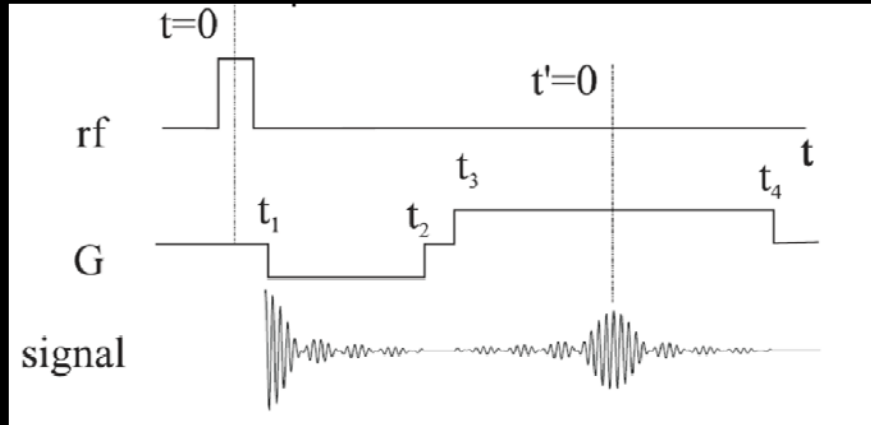
Sampling time was denoted as T_s



Slice Selection and Multidimensional Imaging

- Slice excitation and Bandwidth
- Phase encoding (2D imaging)
- 3D imaging
- k -space trajectories

Imaging Equation



$$S(t) = \int dz \cdot \rho(z) \cdot e^{-i \cdot \gamma \cdot G_z \cdot z \cdot t}$$

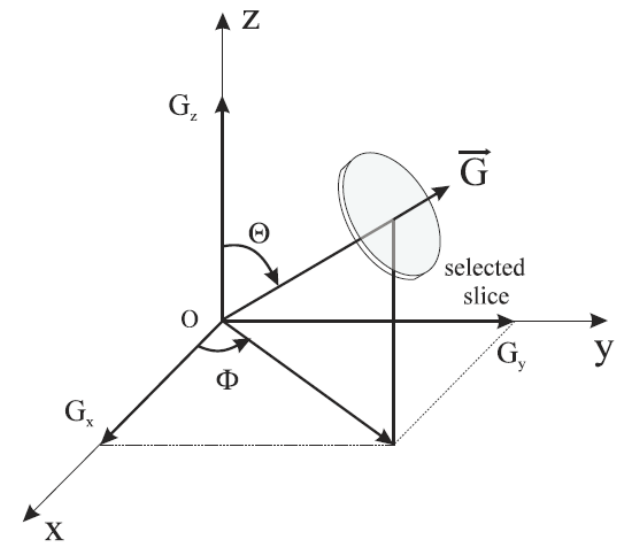
$$k_z(t) = \int_0^t \gamma \cdot G_z(t') \cdot dt' \quad \phi(z, t) = -2\pi \cdot k_z(t) \cdot z$$

$$S(t) = S(k_z) = \int dz \cdot \rho(z) \cdot e^{-i \cdot 2\pi \cdot k_z \cdot z}$$

$$\begin{aligned} \vec{G}(t) &\equiv \vec{\nabla} B_z^g(\vec{r}) \\ &= \hat{x} \frac{\partial}{\partial x} B_z^g + \hat{y} \frac{\partial}{\partial y} B_z^g + \hat{z} \frac{\partial}{\partial z} B_z^g \\ &\equiv G_x(t) \hat{x} + G_y(t) \hat{y} + G_z(t) \hat{z} \end{aligned}$$

$$\phi(\vec{r}, t) = -\gamma \vec{r} \cdot \int_0^t dt' \vec{G}(t') \quad \vec{k}(t) = -\gamma \int_0^t dt' \vec{G}(t')$$

$$s(\vec{k}) = \int d^3r \rho(\vec{r}) e^{-i 2\pi \vec{k} \cdot \vec{r}}$$



Imaging Equation

1D: $s(k_x) = \int dx \cdot \rho(x) \cdot e^{-i \cdot 2 \cdot \pi \cdot k \cdot x}$



$$x \rightarrow \vec{r} = (x, y, z)$$

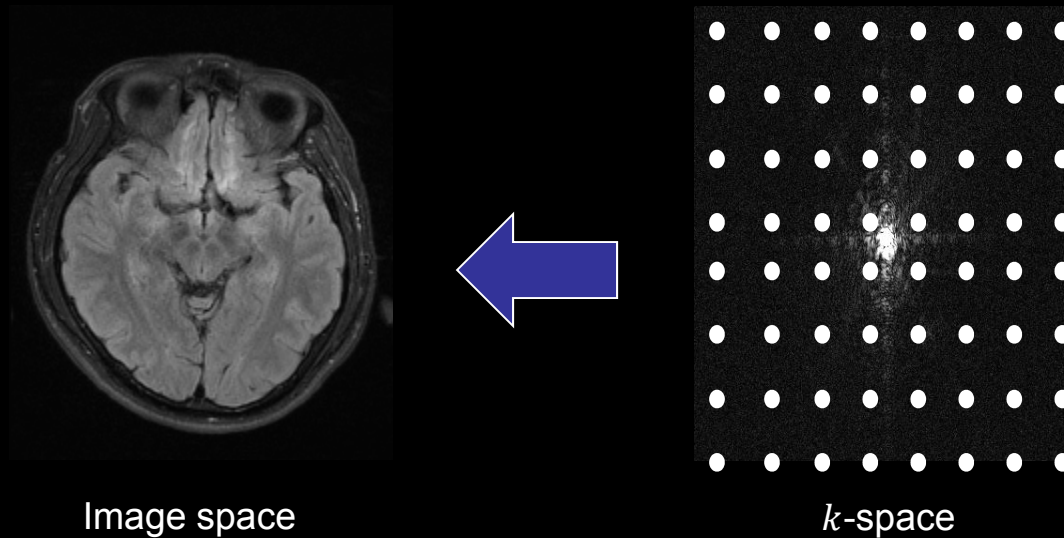
3D: $s(k) = \int d^3r \cdot \rho(r) \cdot e^{-i2\pi(\vec{r} \cdot \vec{k})}$

- 1) All dimensions are equivalent
- 2) k along each direction is determined by the gradient in that direction

$$\begin{aligned} s(k_x, k_y, k_z) \\ = \iiint dx \cdot dy \cdot dz \cdot \rho(x, y, z) \cdot e^{-i2\pi(k_x x + k_y y + k_z z)} \end{aligned}$$

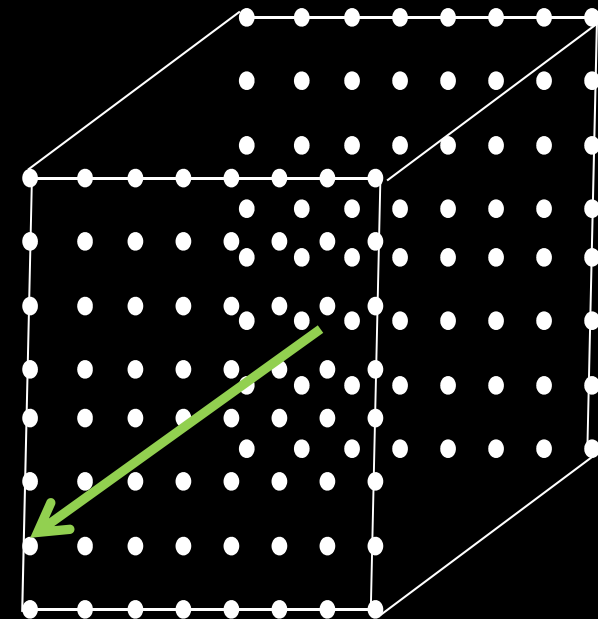
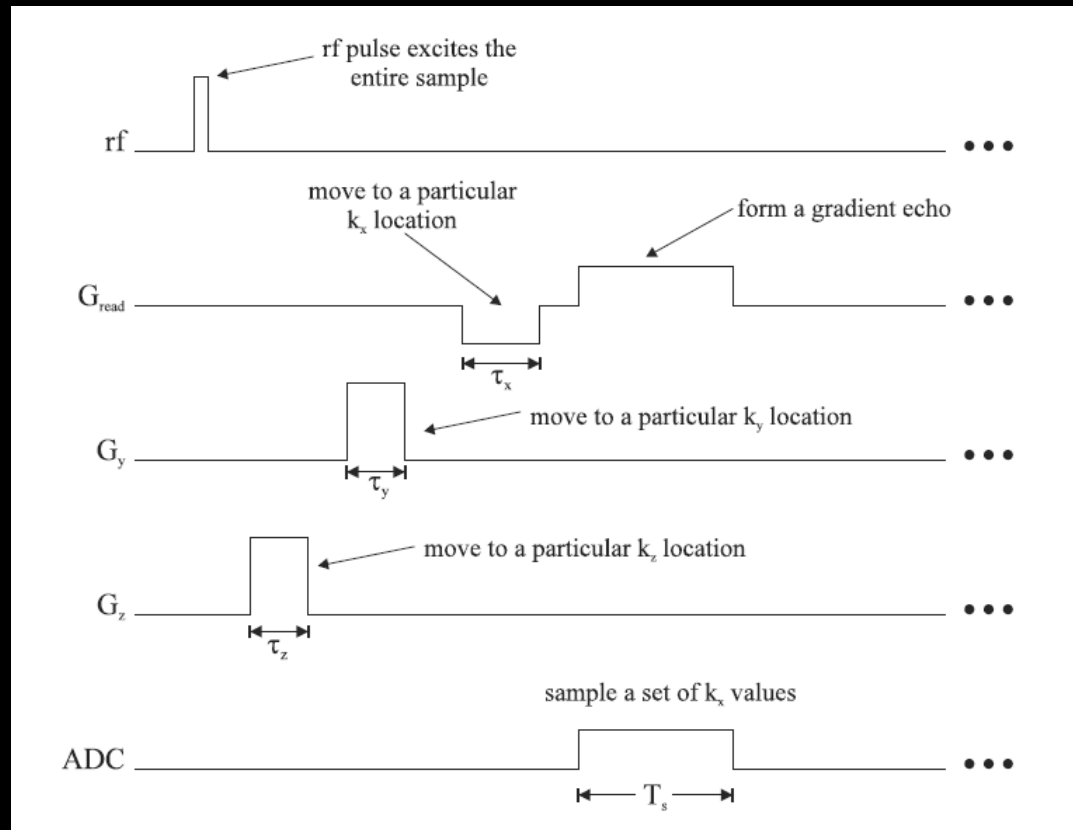
$$k_x(t) = \gamma \int^t G_x(t') dt', \quad k_y(t) = \gamma \int^t G_y(t') dt', \quad k_z(t) = \gamma \int^t G_z(t') dt'$$

Imaging Equation



Filling up the corresponding 2D/3D k -space to obtain the image

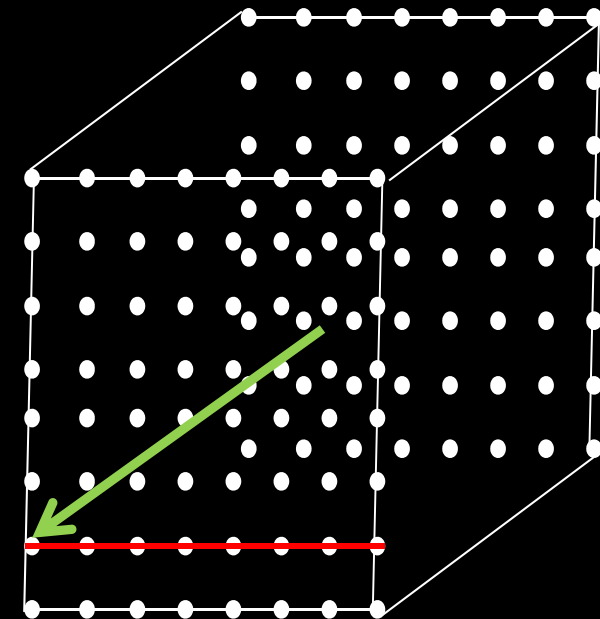
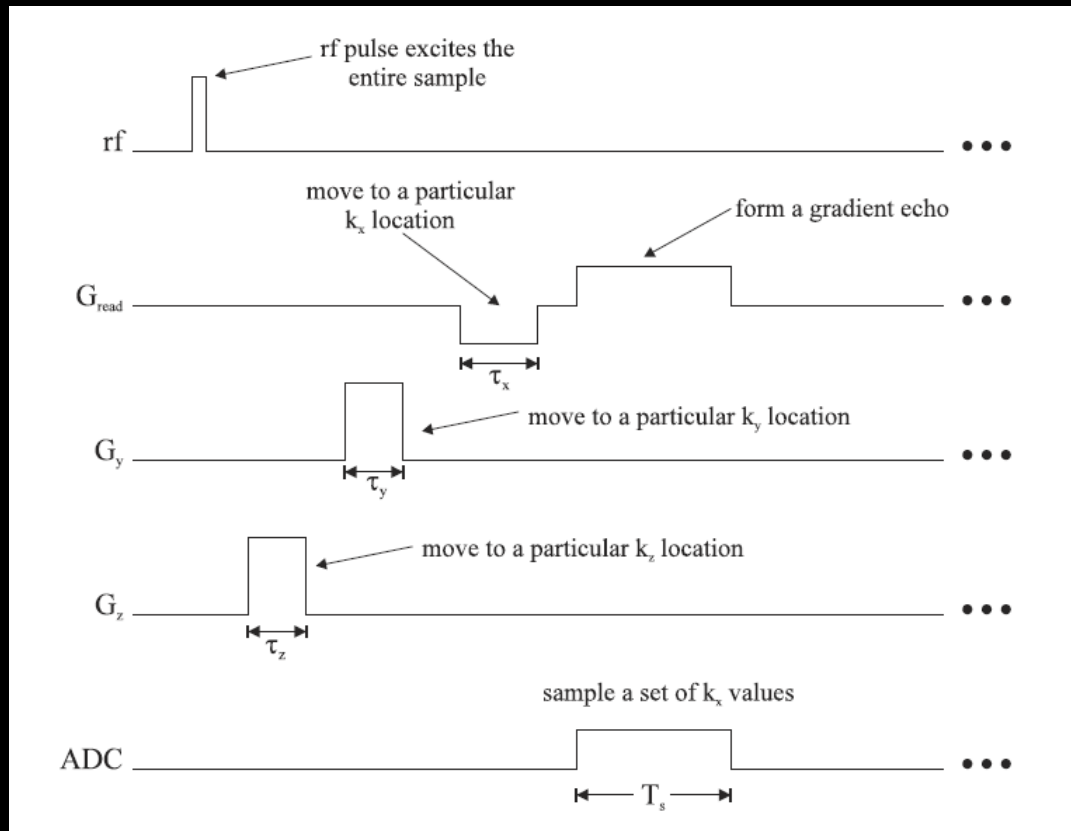
Multidimensional Spatial Encoding (2D/3D imaging)



$$k_y = \bar{\gamma} \cdot G_y \cdot \tau_y$$

$$k_x(t) = \gamma \int^t G_x(t') dt', \quad k_y(t) = \gamma \int^t G_y(t') dt', \quad k_z(t) = \gamma \int^t G_z(t') dt'$$

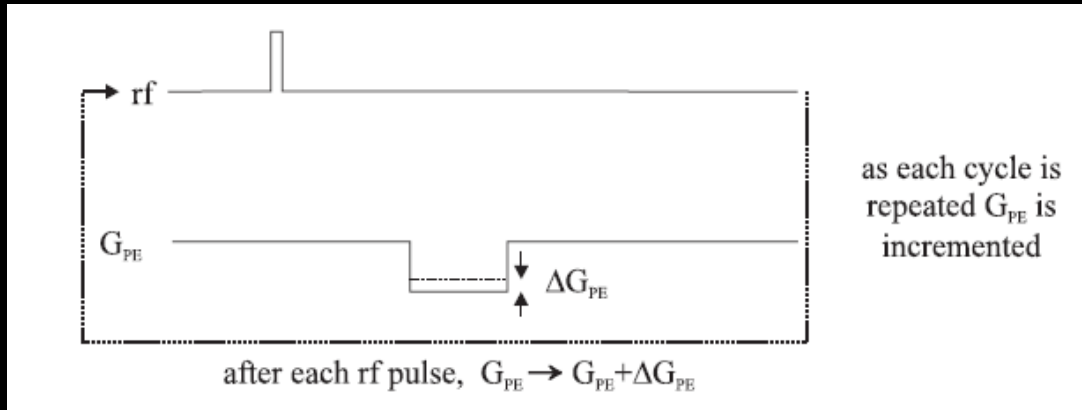
Multidimensional Spatial Encoding (2D/3D imaging)



$$k_y = \bar{\gamma} \cdot G_y \cdot \tau_y$$

$$k_x(t) = \gamma \int^t G_x(t') dt', \quad k_y(t) = \gamma \int^t G_y(t') dt', \quad k_z(t) = \gamma \int^t G_z(t') dt'$$

Phase encoding



Phase encoding

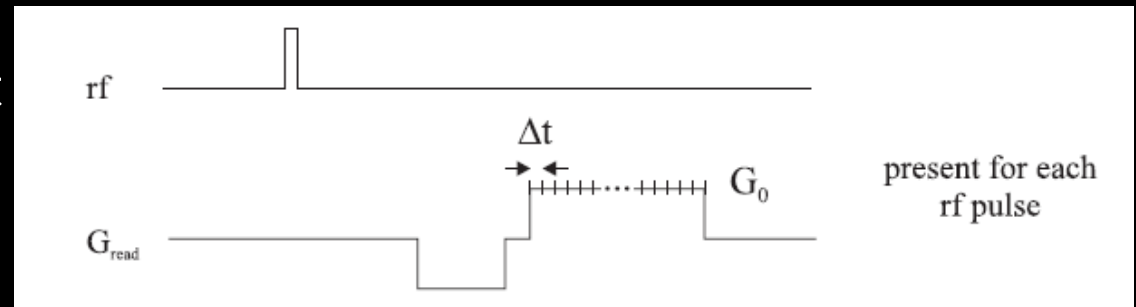
$$\Delta k_y = -\bar{\gamma} \cdot \Delta G_y \cdot \tau$$

Encoding phase is accumulated in steps of the phase encoding gradient

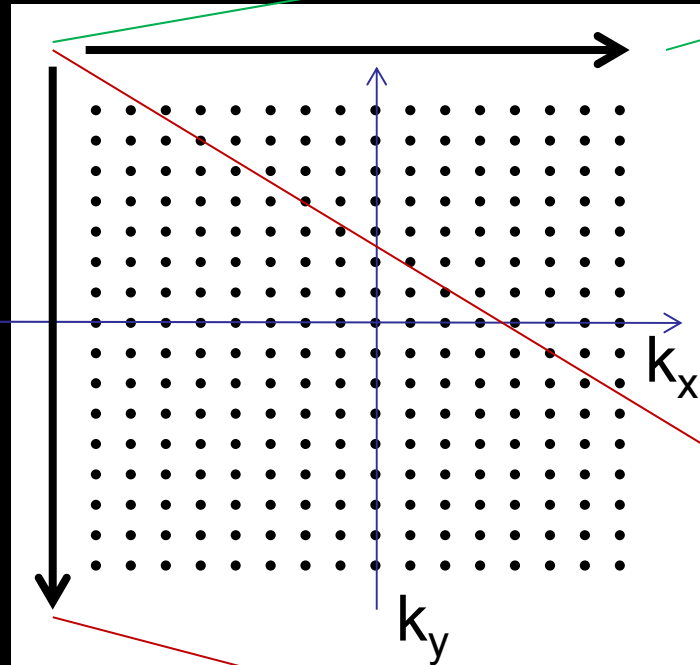
Frequency encoding

$$k_x = \gamma \cdot G_x \cdot t = \gamma \cdot G_x \cdot \Delta t$$

Encoding phase is accumulated with the progression of time

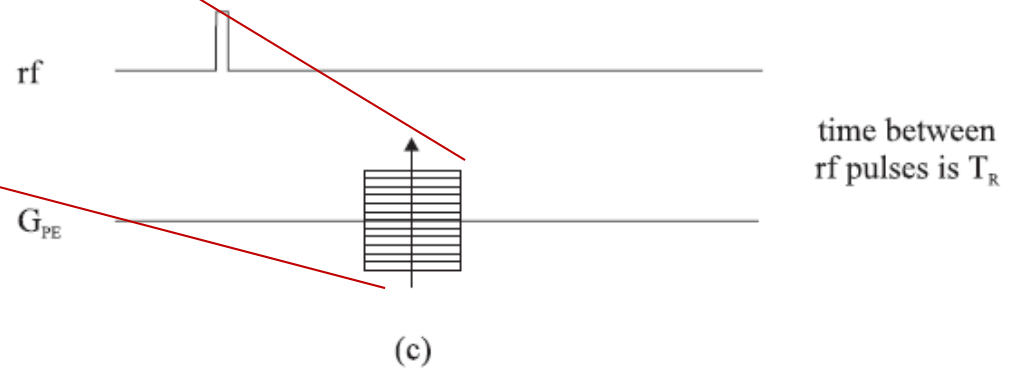
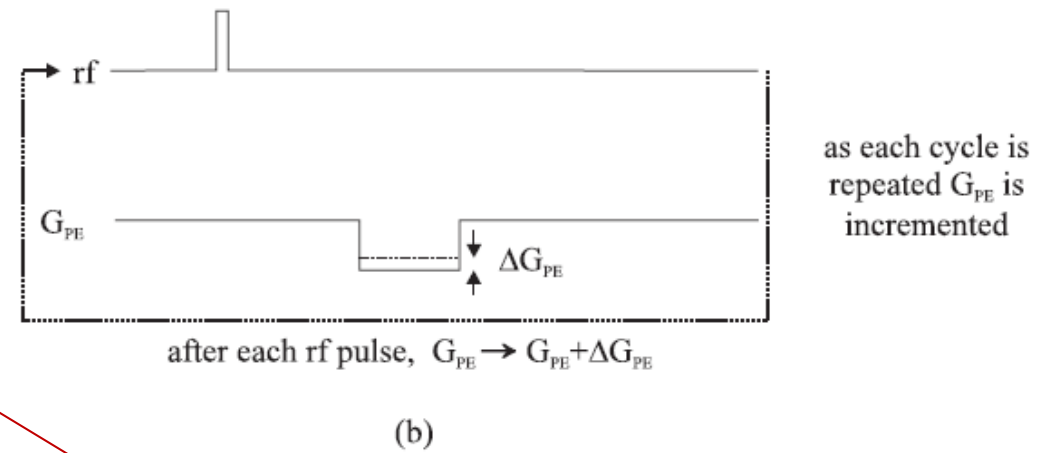
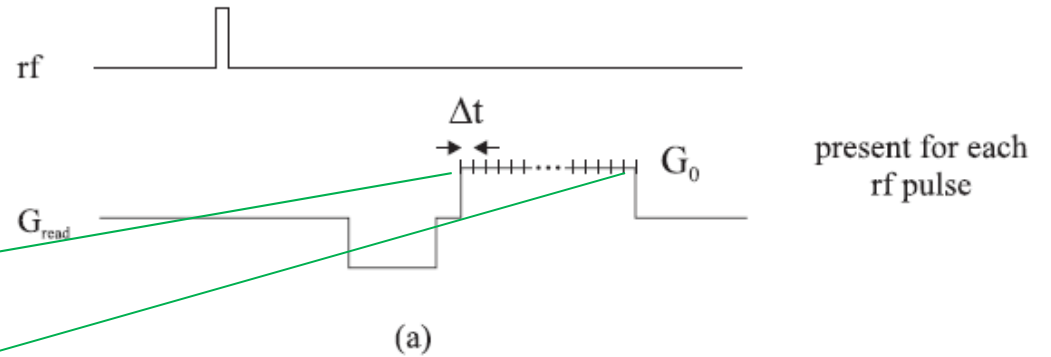


Phase encoding

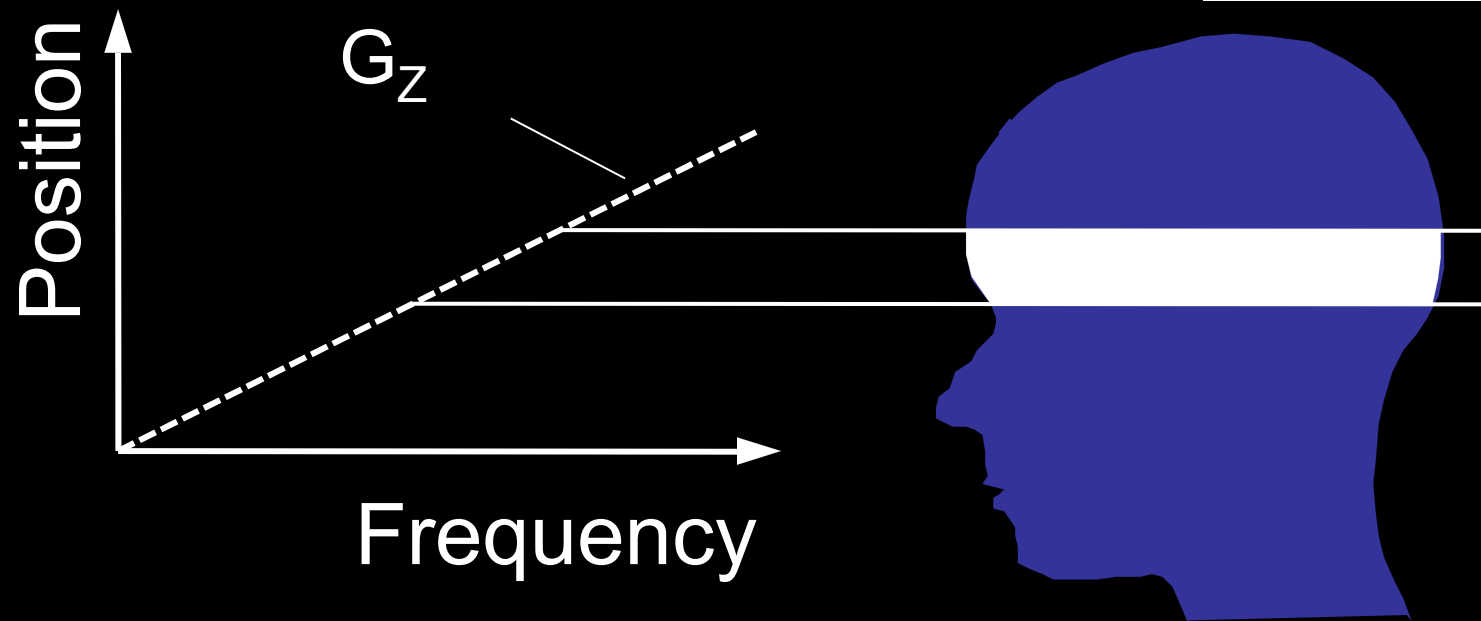
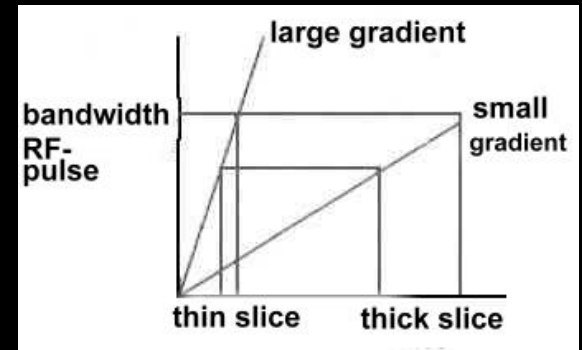


$$k_y = \gamma \cdot G_y \cdot t$$

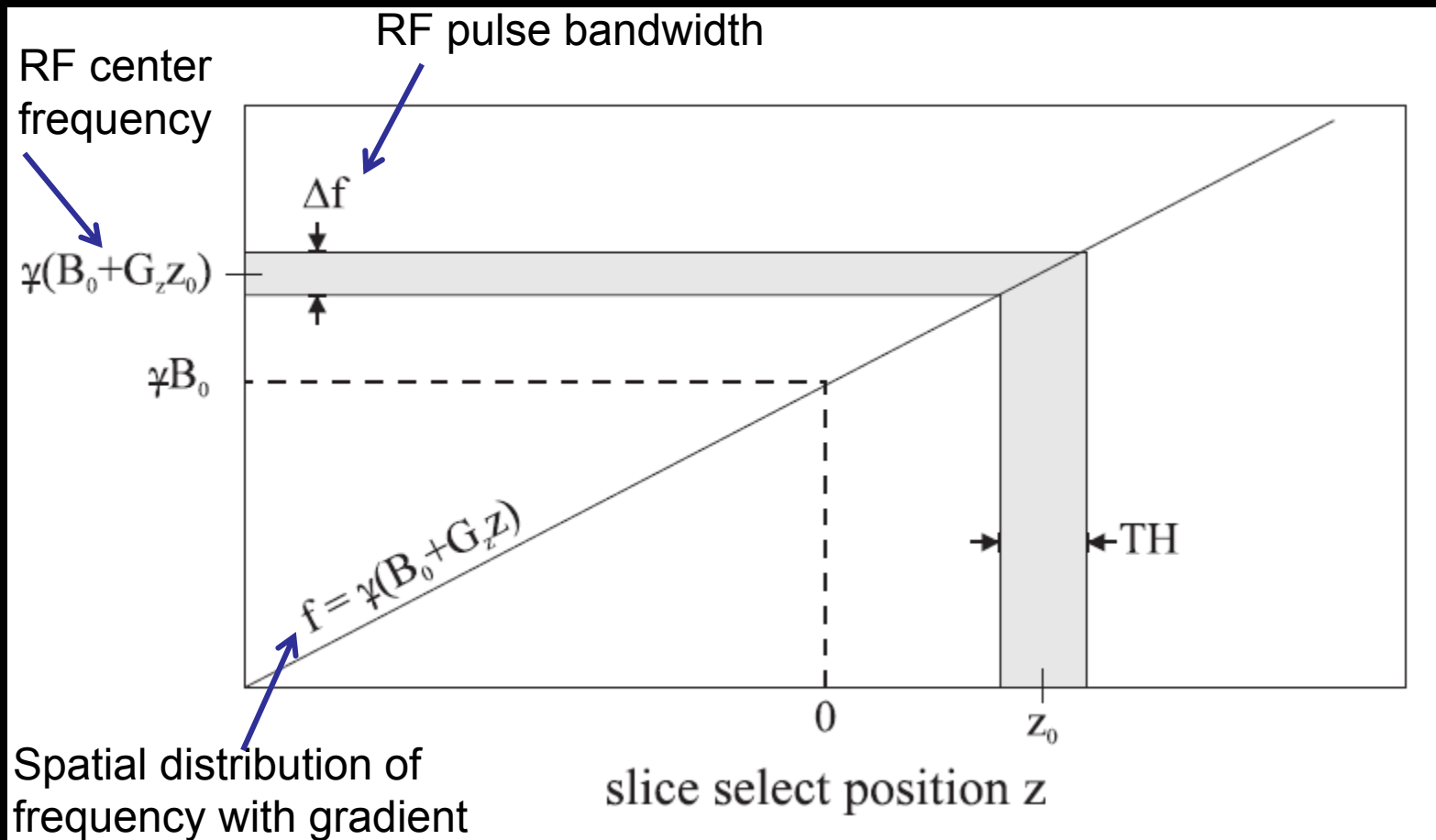
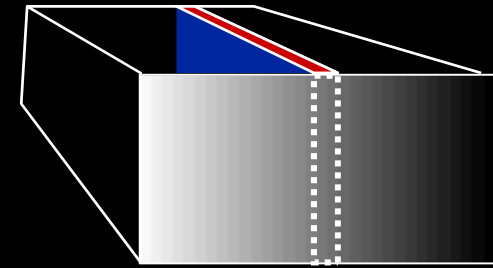
$$= \gamma \cdot \Delta G_y \cdot \tau$$



Slice Selection

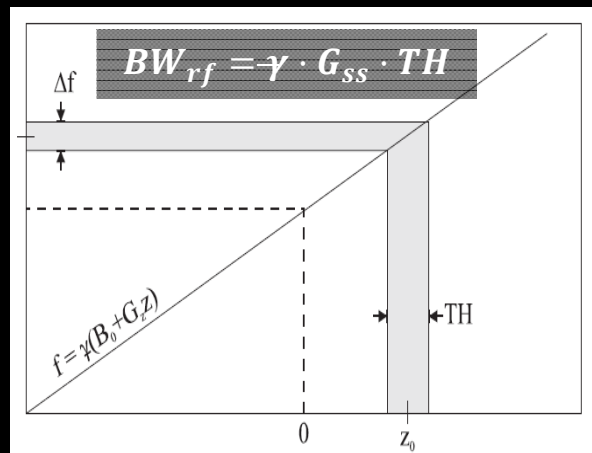


Slice selection



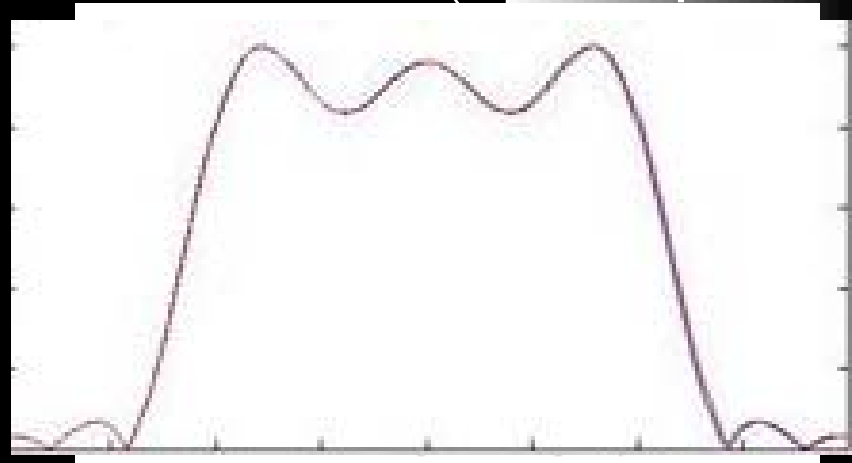
Slice selection

Slice selection

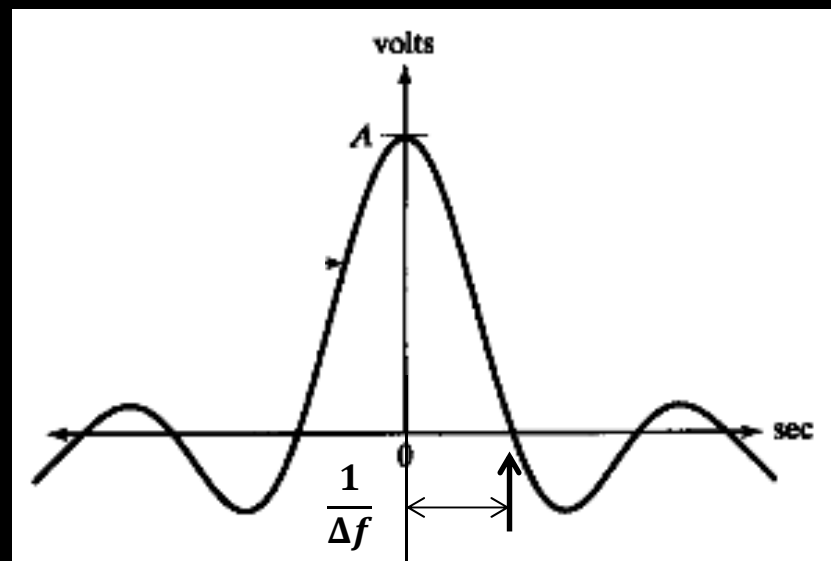


$$\Delta f = BW_{rf}$$

$$\tau_{rf} = n_{zc} \cdot \left(\frac{1}{BW_{rf}} \right)$$



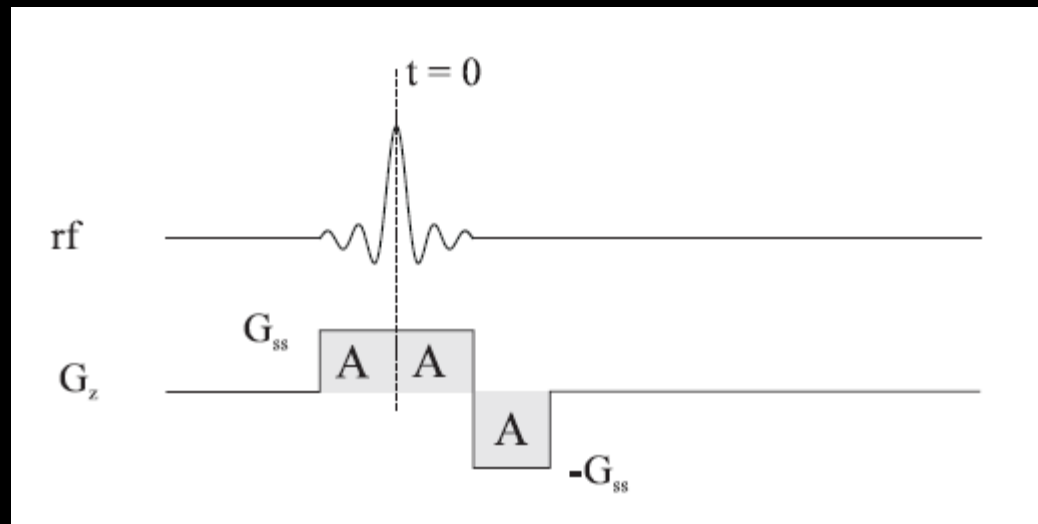
$$BW_{rf} = \Delta f = \gamma \cdot G_{ss} \cdot TH$$



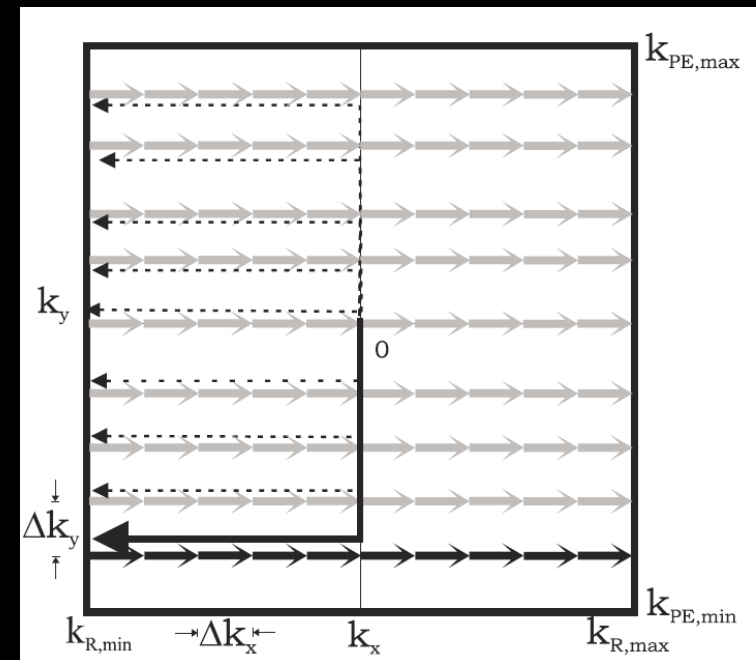
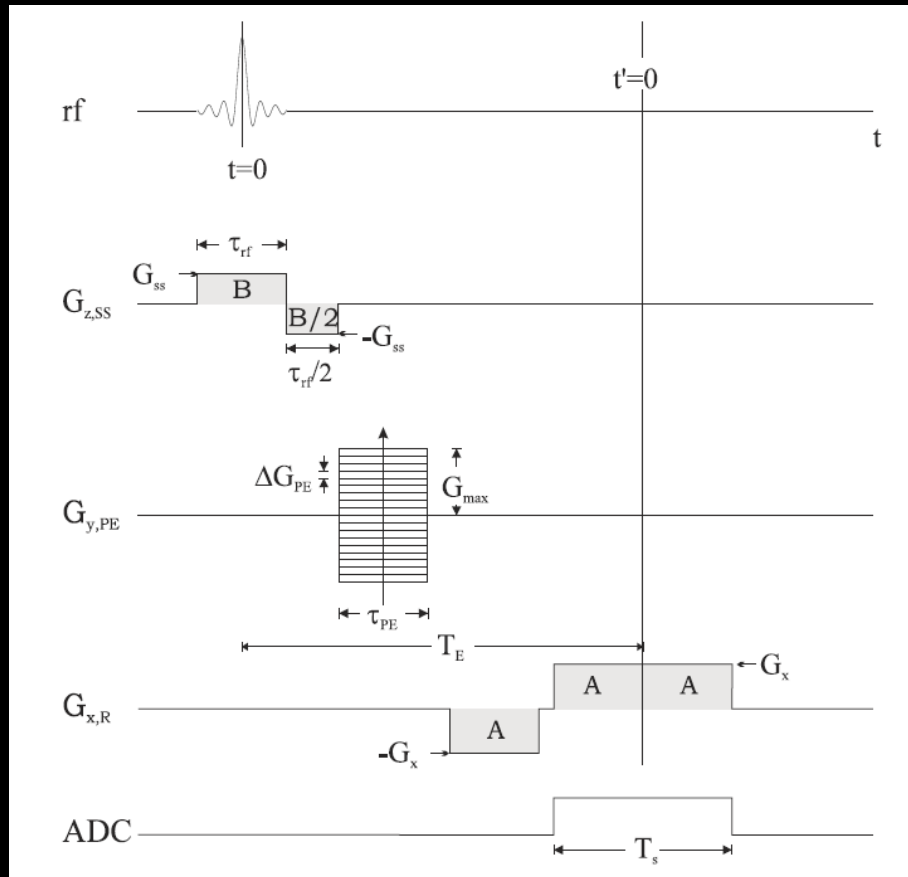
Slice selection gradient refocusing

Spin dephasing during excitation

Spins are considered instantaneously tipped at the center of RF pulse. So, they start getting dephased under the influence of $G_{ss}(1/2)$

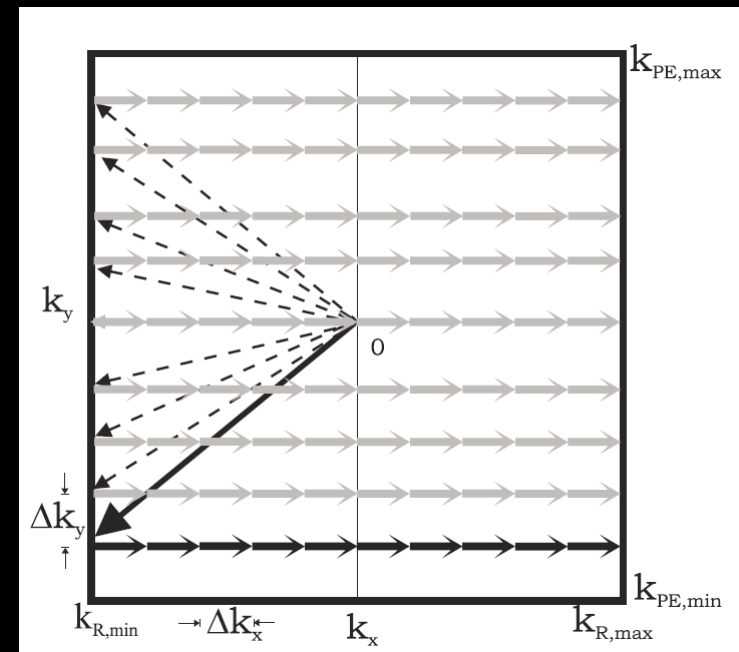
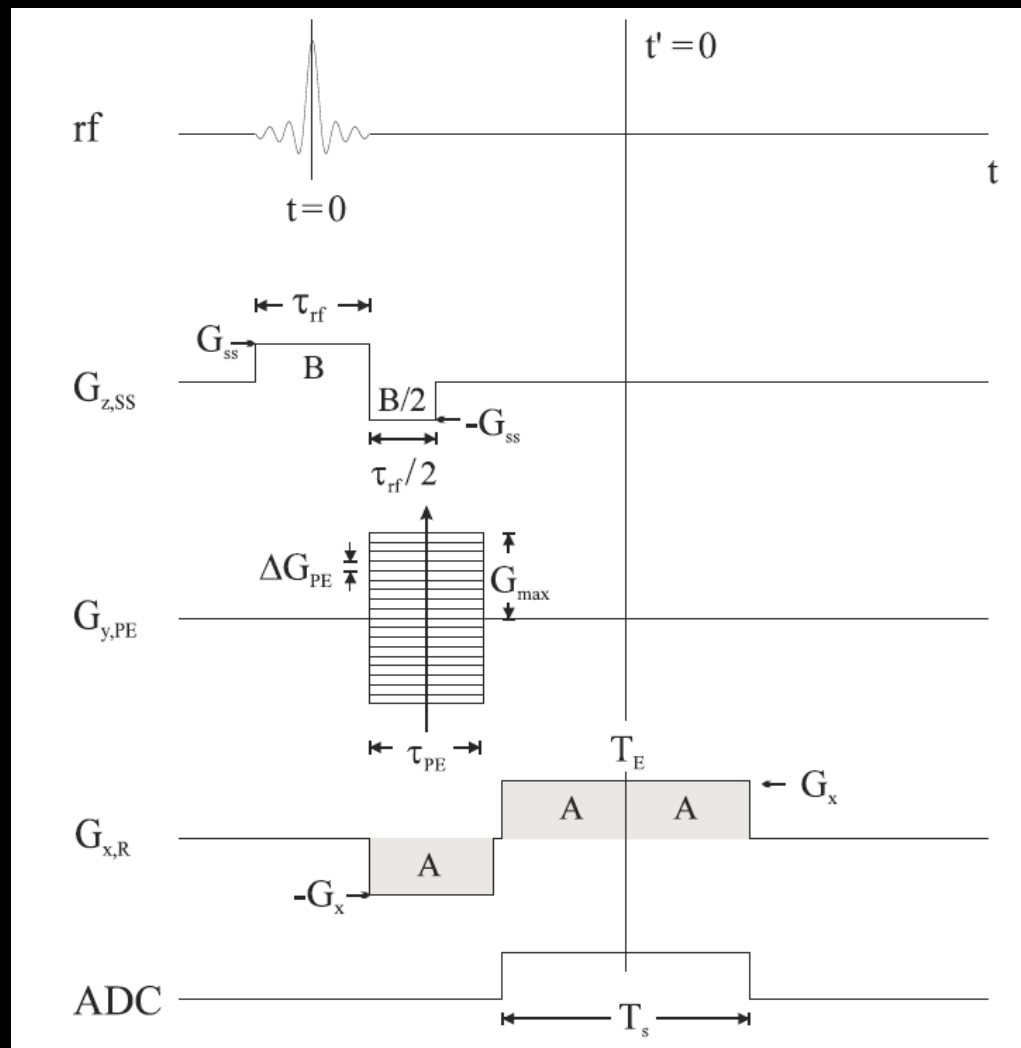


2D Imaging sequence



$$k_{read_min} = \bar{\gamma} \cdot -G_{read} \cdot \frac{T_s}{2}$$

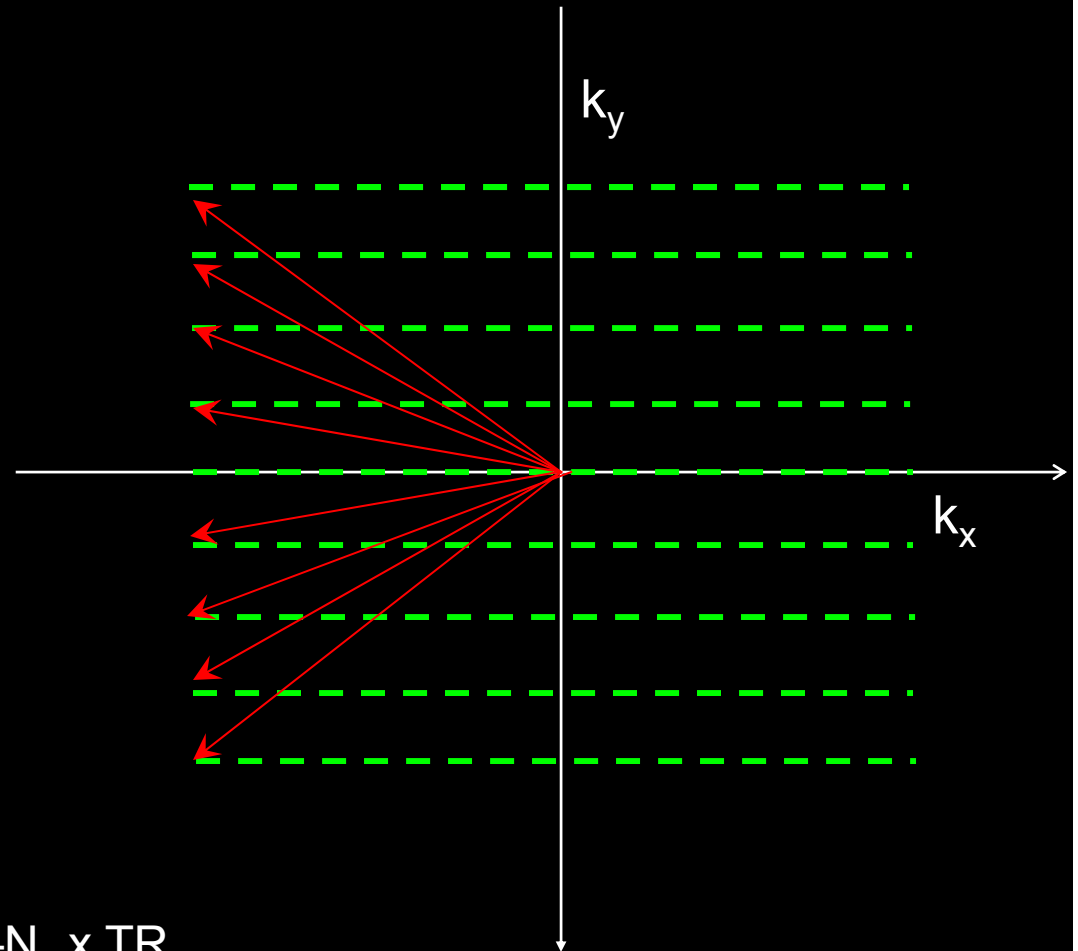
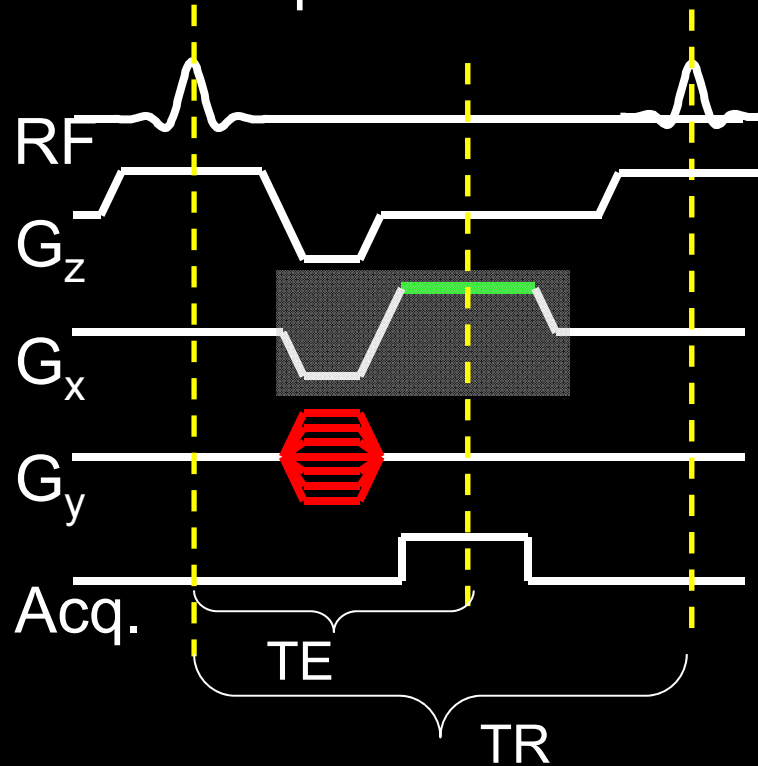
2D Imaging sequence



$$k_{read_min} = \bar{\gamma} \cdot -G_{read} \cdot \frac{T_s}{2}$$

2D imaging: K-space trajectory

Typical Gradient
Echo sequence

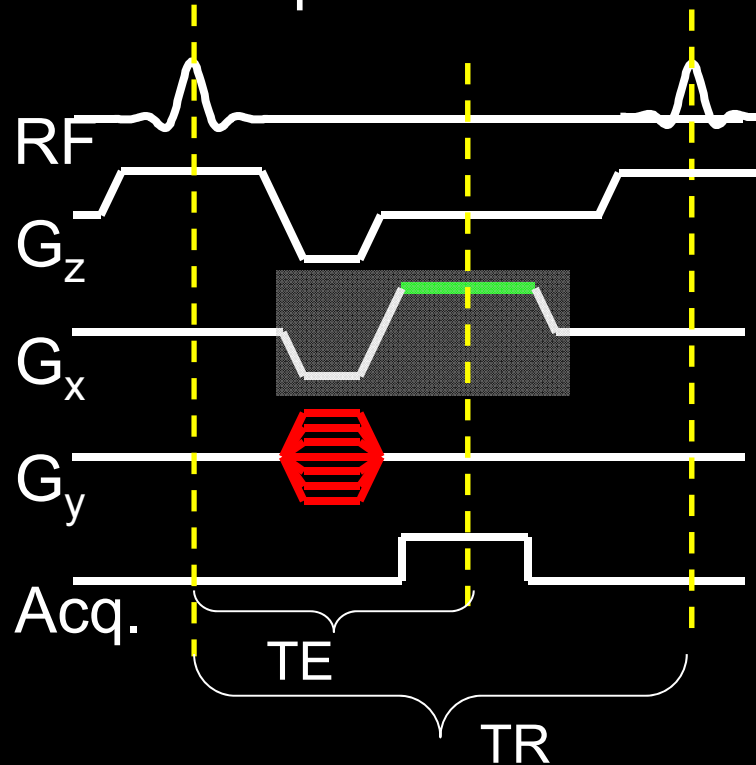


Total imaging time for a single slice $-N_y \times TR$

Sampling of the signal line by line forming the image in
Spatial frequency domain

2D imaging: acquiring line by line

Typical Gradient
Echo sequence



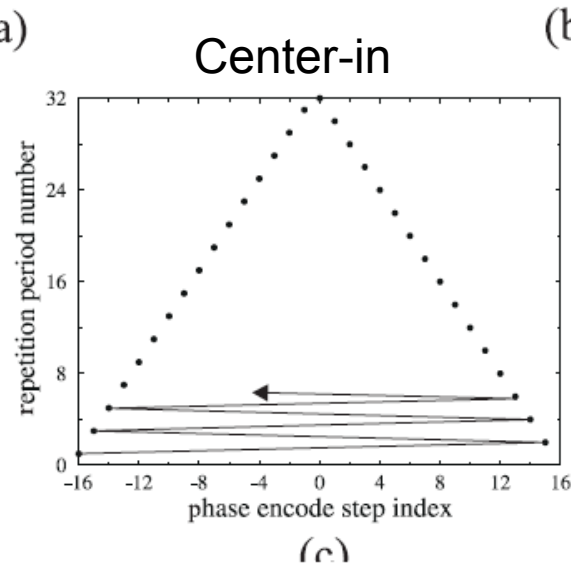
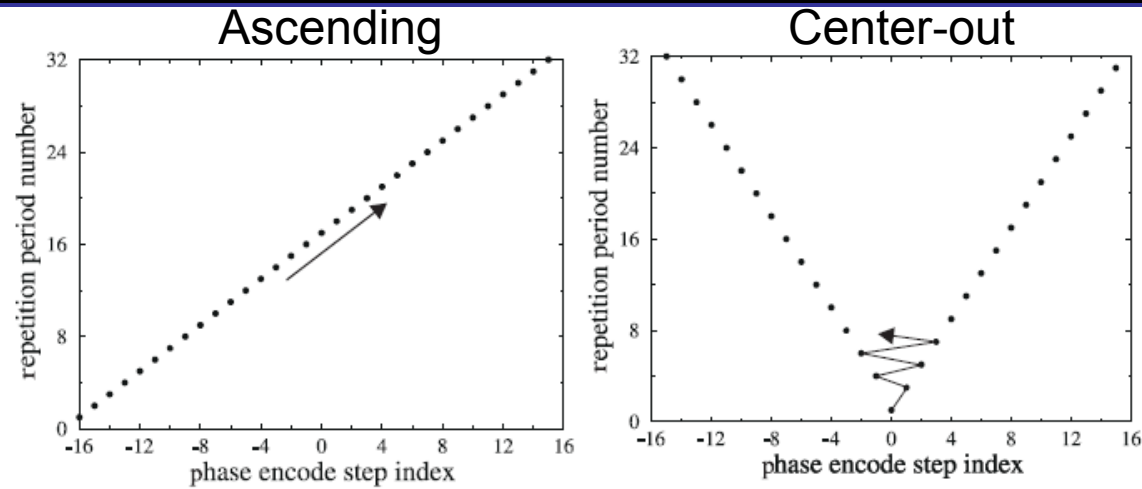
k-space

Image space

Total imaging time for a single slice $-N_y \times TR$

Sampling of the signal line by line forming the image in
Spatial frequency domain

Phase encoding order (Cartesian)

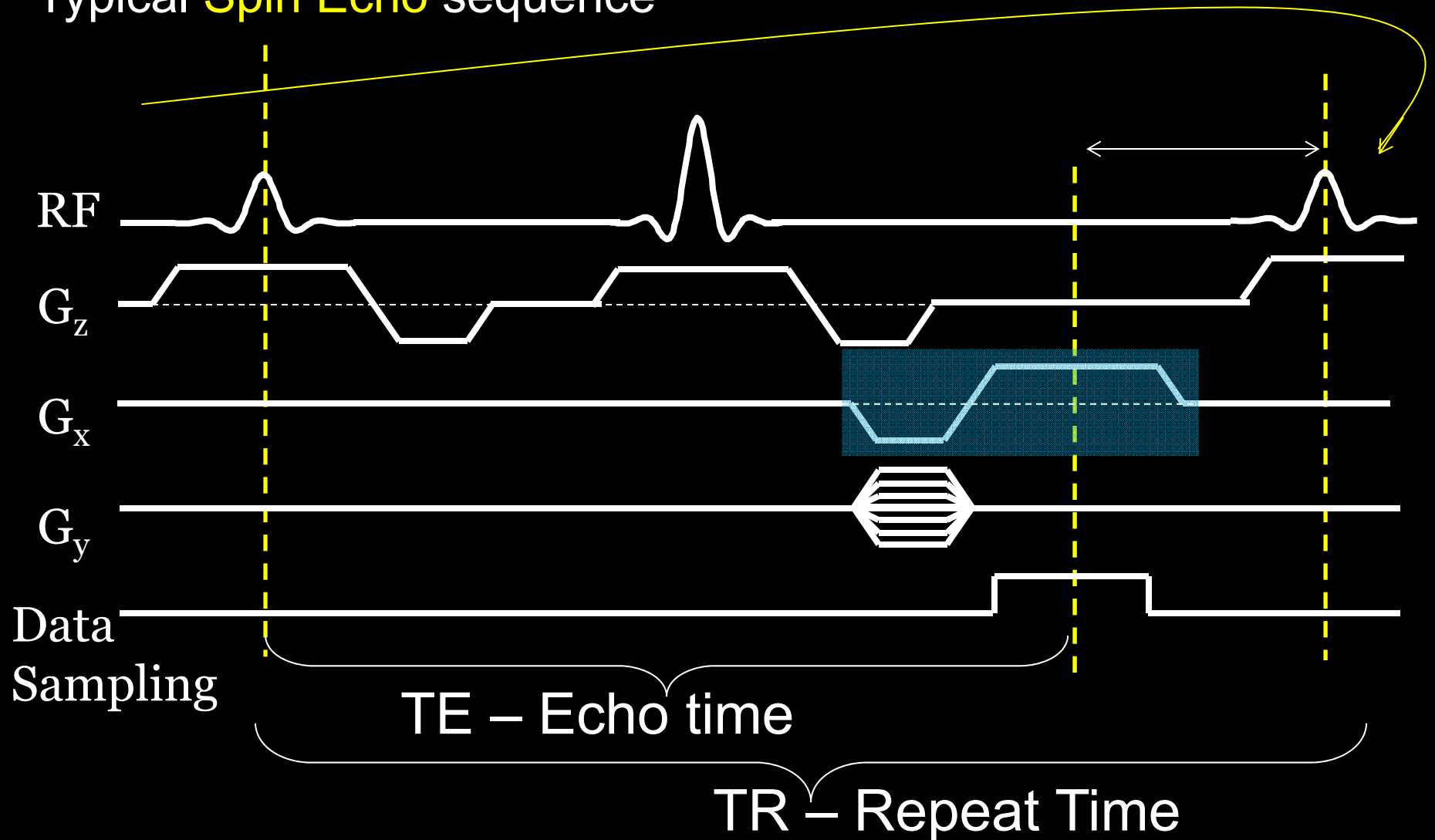


Phase Encoding vs. Frequency Encoding

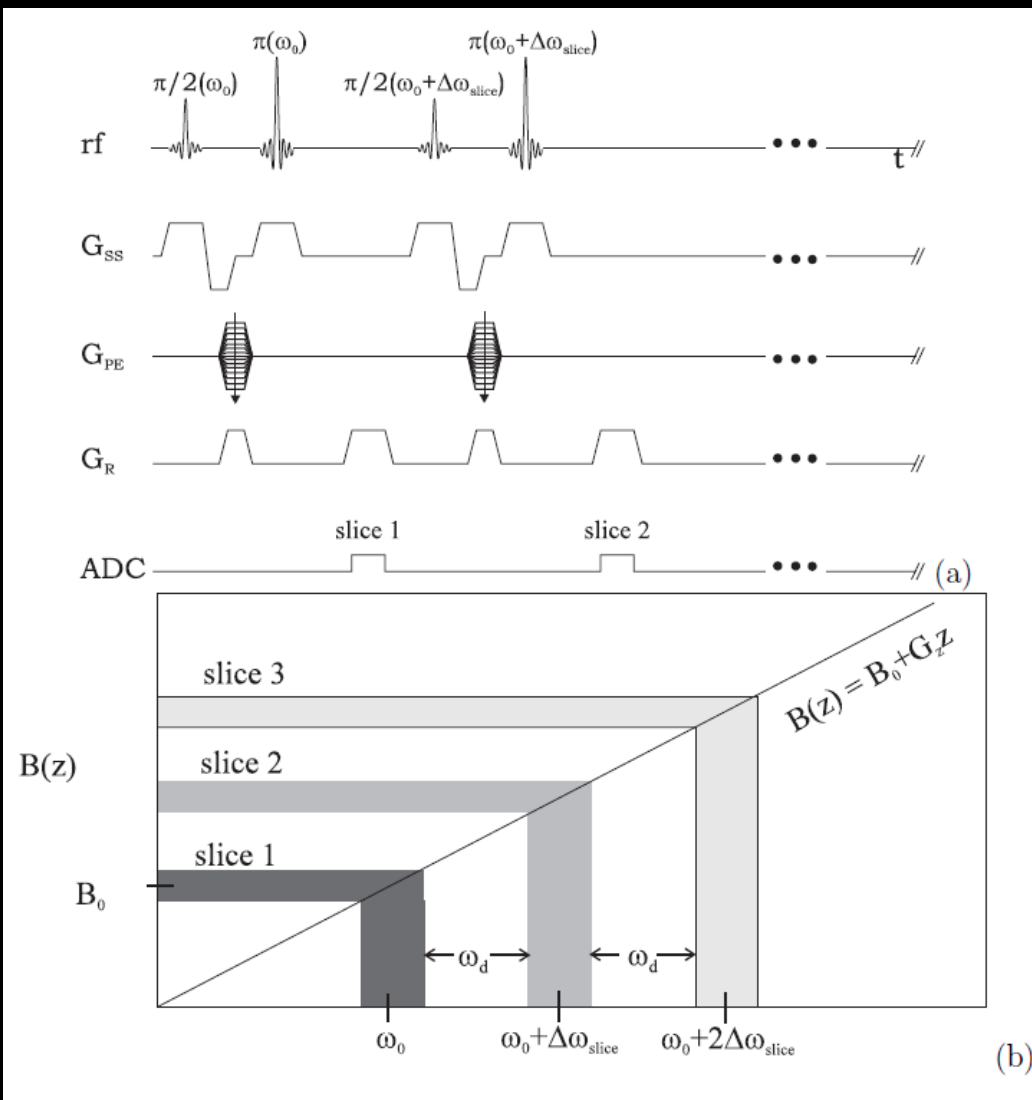
- Acquisition: Discrete vs continuous accrual of phase
- Time-distance between every adjacent points along phase vs frequency encoding is different (Δt vs TR)
- Difference in time between position encoding and data acquisition
- Spatial/k direction

Acquiring the data... line by line

Typical **Spin Echo** sequence

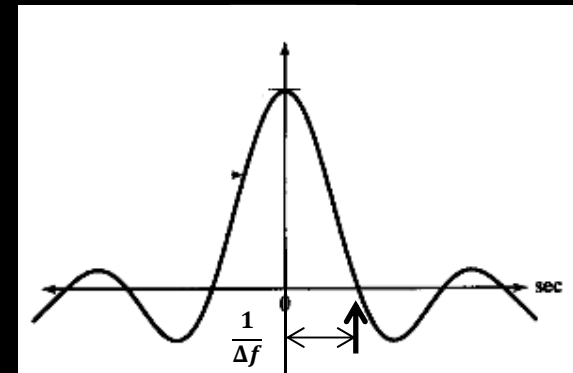
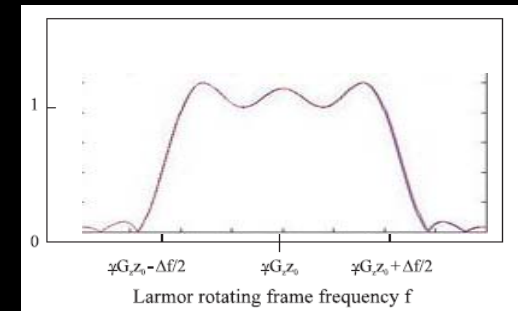
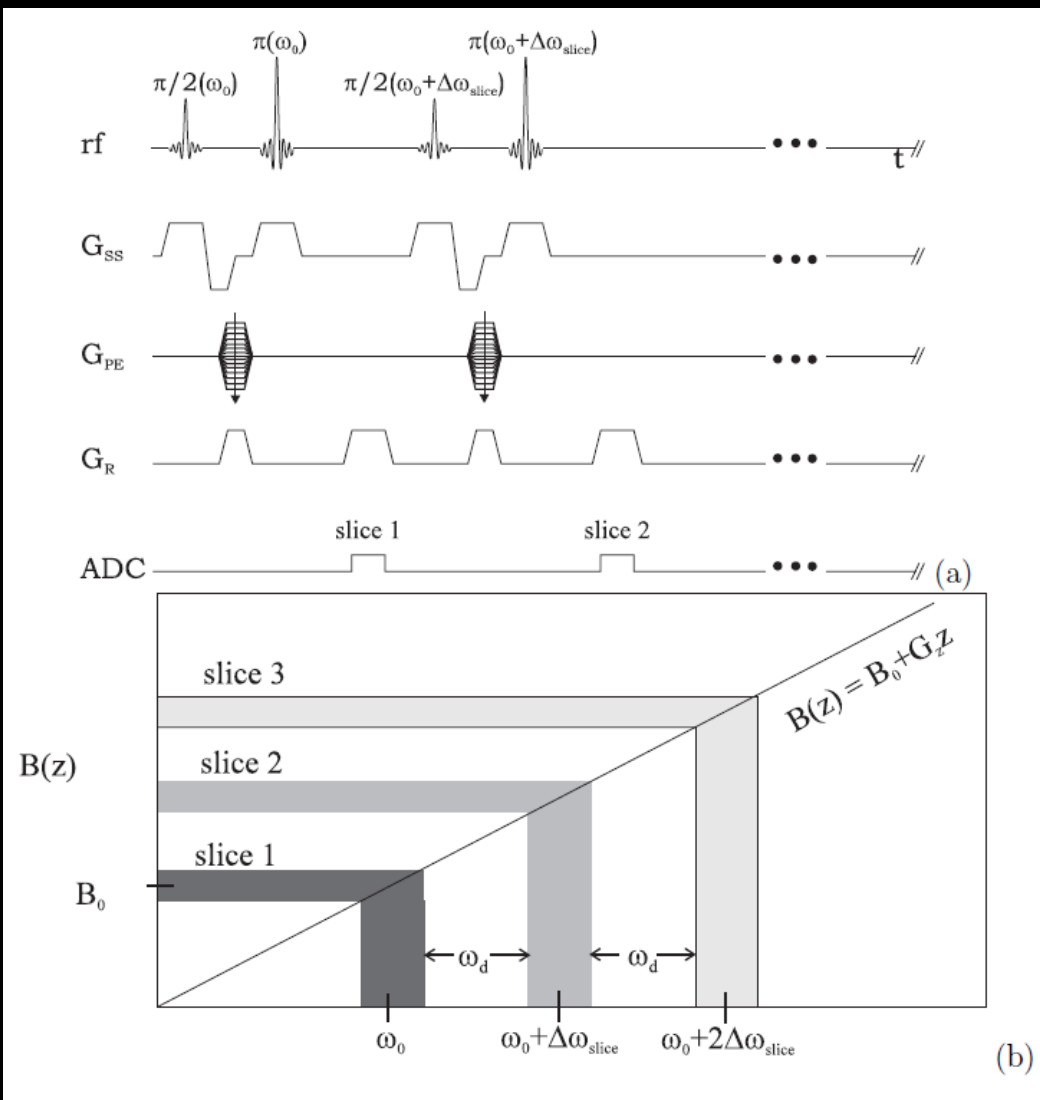


Multi-slice 2D imaging



- Using the dead time to acquire data from multiple slices within the same TR
- Same G_{ss} but varying RF center frequency
- Slice gap is usually needed due to imperfect RF frequency profiles

Multi-slice 2D imaging

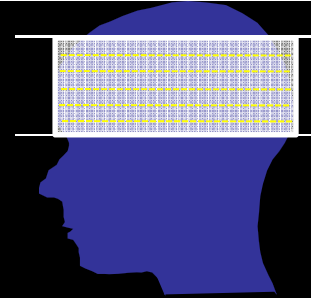


$$\gamma G_{SS}(TH + d) = \Delta\omega_{\text{slice}}$$

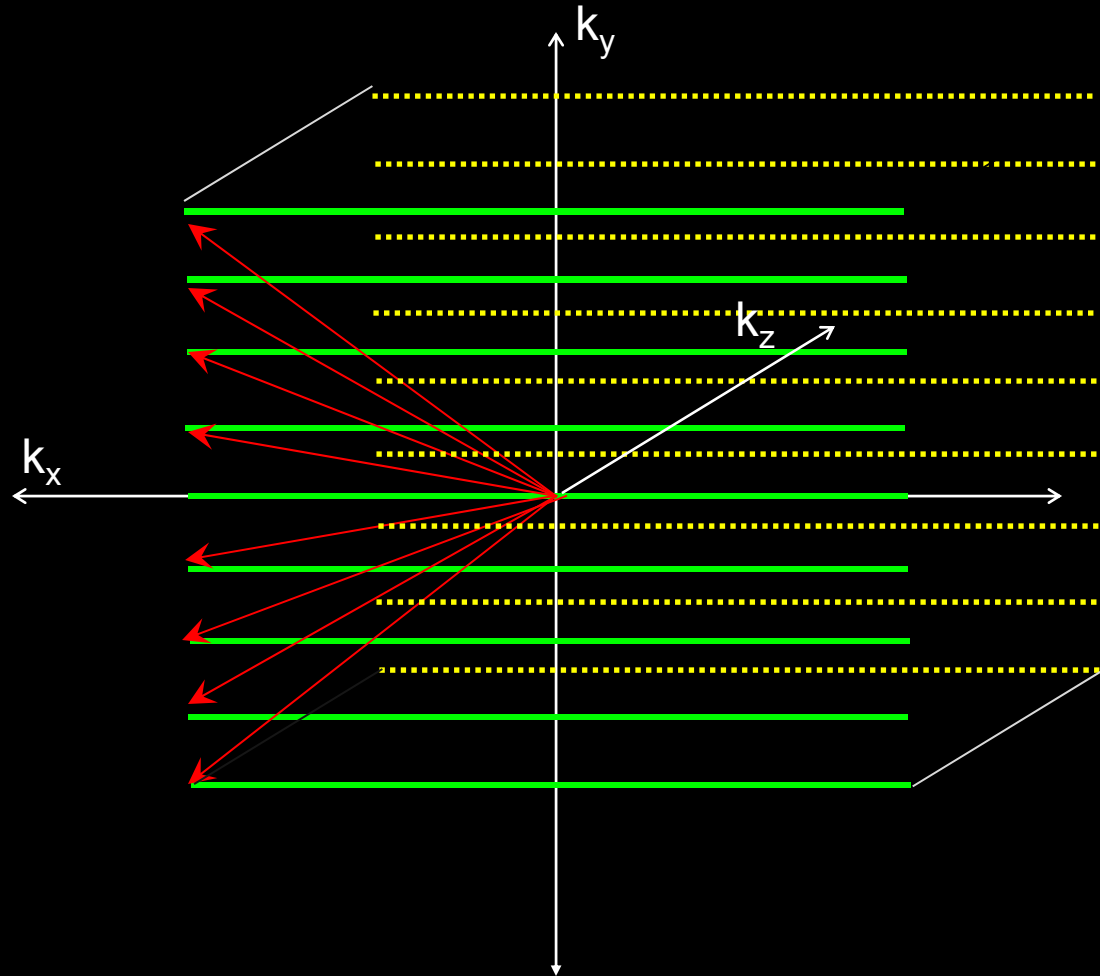
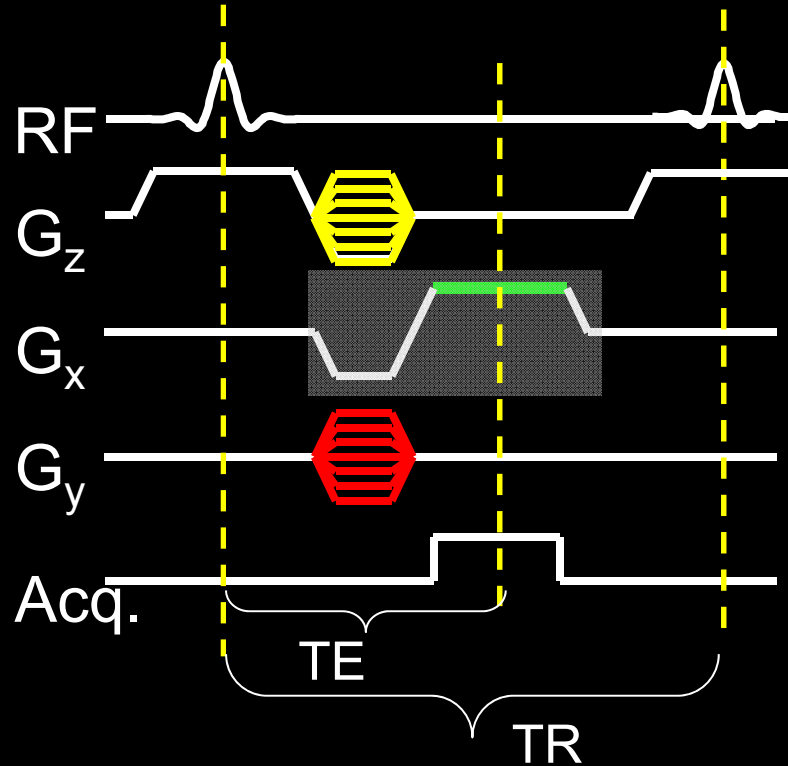
$$d = \frac{(\Delta\omega_{\text{slice}} - 2\pi BW_{rf})}{\gamma G_S}$$

Slice interleaved acquisition - Odd/Even

3D volumetric imaging



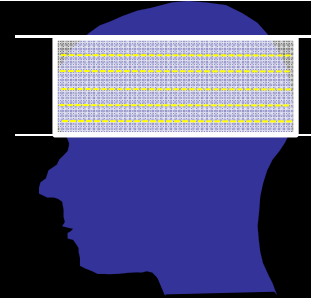
3D GRE - with slab excitation and partition encoding



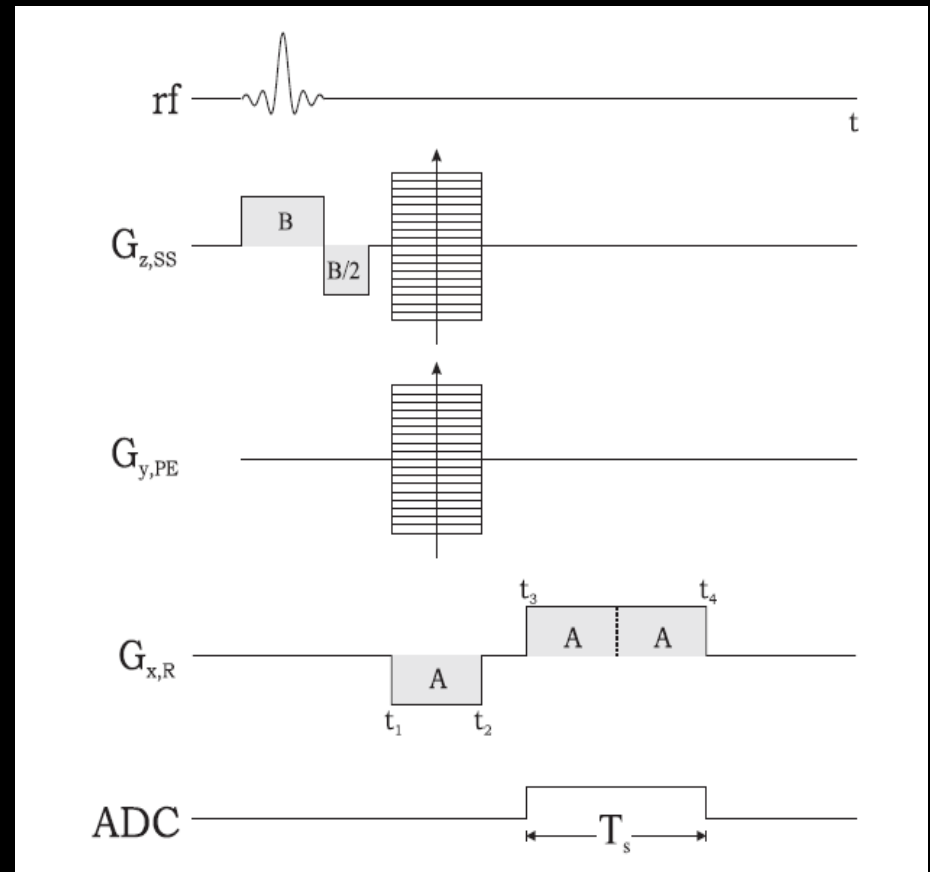
Total Imaging time – $N_z \times N_y \times TR$

Slab Excitation and partition encoding in the z direction.

3D imaging



- Additional PE along slice selection
- Volumetric excitation (slab instead of slice)
- 3D iFFT
- Pros (vs. multi-slice 2D):
 - High resolution on SS dimension
 - High SNR
- Cons (vs. multi-slice 2D):
 - Longer scan time
 - Min slice# per slab for FFT
 - Sensitive to motion



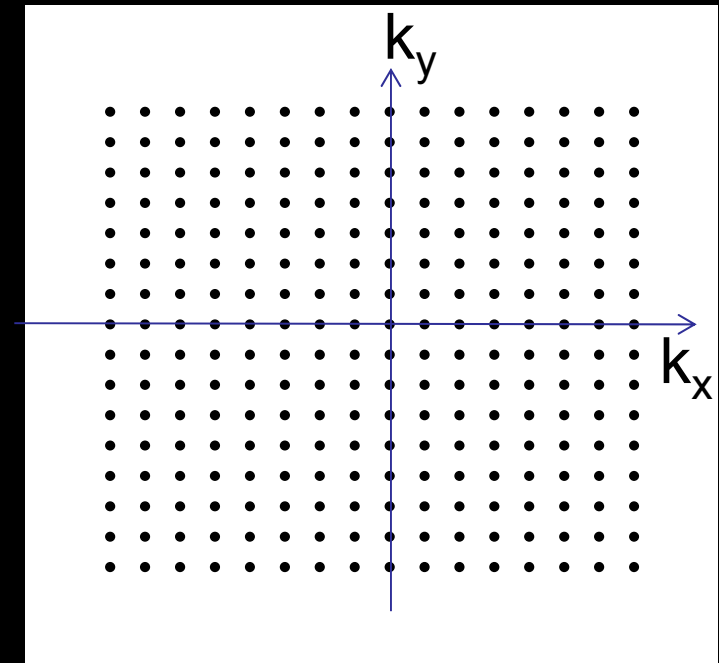
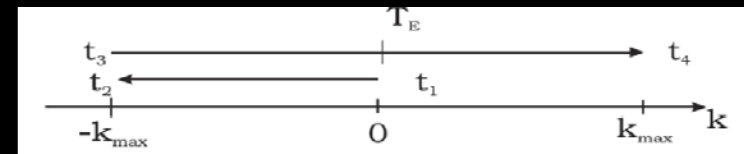
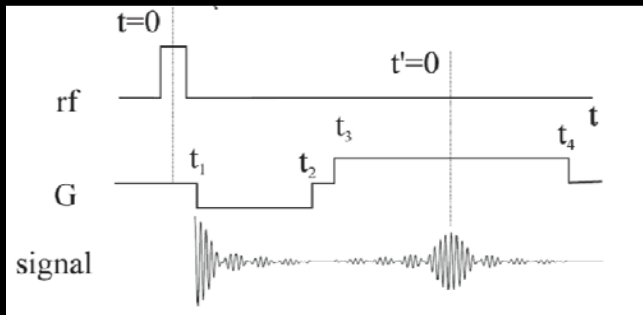
Homework

- Probs. 10.1 - 10.4, 10.7

Next Session

Chapter 11 and 12.1-12.2

Multidimensional Spatial Encoding (2D/3D imaging)



$$S(k_x) = \int dx \cdot \rho(x) \cdot e^{-i \cdot \phi_x}$$

$$\phi_x = \gamma \cdot G_x \cdot \Delta t \cdot x = -2\pi \cdot \Delta k_x \cdot x$$